# Rule-Guided Knowledge-Graph based Negative Sampling for Outfit Recommendation

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Recommender system (RS) has become increasingly prevalent among online service providers. The effectiveness of an accurate RS highly relies on the quality level of the selected negative instances for training. Most of the existing negative sampling strategies either merely leverage the interaction data which suffer from the sparsity challenge or fail to fully utilize the side information. To address these issues, we introduce rule-guided knowledge graph (RuleKG) by integrating the enriched relations of the knowledge graph (KG) and categoryaware fashion rules into the outfit recommendation problem. The rules are further incorporated into a newly designed score function which represents the user's preferences toward outfit in a more finegrained perspective. Given a user-outfit pair, the negative candidates are explored in both outfit- and user-level. Also, the reinforcement learning (RL)-based strategy is developed to automatically choose the next state from the starting point over KG. Experimental results on the new top-bottom outfit dataset demonstrate the superiority of the proposed approach and the generality of the negative sampler model is validated on the music recommendation benchmark.

## CCS CONCEPTS

• Information systems → Recommender systems; Recommender systems; Personalization.

# **KEYWORDS**

Recommender system, knowledge graph, negative sampling, reinforcement learning

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Fig. 1: Examples of users and the outfits they interact with diverse category combinations.

## **1 INTRODUCTION**

In recent years, we have witnessed the widespread application of the recommender system in a variety of real-world scenarios [6, 7, 10, 17, 26, 27, 31]. Even though traditional matrix factorization (MF)-based approaches [9] have achieved excellent performances, it suffers from data sparsity problem. Knowledge-aware framework in the context of knowledge graph aims to resolve these issues by exploiting auxiliary data sources [5]. Moreover, the quality of the negative user-item pairs has a significant impact on the recommendation accuracy. Existing negative sampling strategies [1, 11, 23, 25, 28] suffer from the problem of vanishing gradient [30]. With the huge success of Generative Adversarial Network (GAN) [4] in modeling the dynamic distribution of negative instances, IRGAN [18] and KBGAN [2] propose to view the generator as sampler, which is trained in a minimax game with the discriminator. However, these negative sampling approaches don't fully exploit the advantage of KG.

Recent studies [19, 22, 24, 32] have demonstrated the success of incorporating the knowledge graph into reinforcement learningbased algorithms to formalize the negative sampling processing as a Markov Decision Process (MDP) [15] with properly designed reward functions. It poses great challenges in how to incorporate the RL-based scheme into the knowledge graph framework with rich relations between entities. Also, fine-grained attributes are required to characterize the overall look of the outfit for capturing the user's individual taste. The recent work [22] also employs RL-based strategy for negative sampling. However, the major difference between the proposed approach and theirs is that they explore the negatives based on multi-hop connection over graph and fail to exploit the critical signals of negatives from the user perspective. Fig. 1 illustrates two exemplar users and the outfits they have clicked triggering different category-related fashion matching rules. User 1 prefers the sweater

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goes with the skirt while User 2 is more interested in matching that with shirt.

To address the above-mentioned issues, we propose a novel Rule-Guided Knowledge-Graph based Negative Sampling for Outfit Recommendation (RuleKG) framework, which is comprised of a reinforcement learning-based sampler to generate high-quality negatives and a rule-guided recommender. More specifically, a set of structured category-aware fashion rules are defined based on fashion domain knowledge, which are further leveraged to expand the knowledge graph and incorporated for user preference modeling via a new rule-guided score function. The attention-based graph convolutional network is utilized to differentiate the importance of neighbors revealing the user's distinctive preference for outfits with different category combinations. And we construct a pseudo exposure data leveraging outfit's textual descriptions and the side information provided by KG, which is utilized to form the action space of a hierarchical RL agent. What is more, the user-outfit pairs are converted into triples for negative sampling in the perspective of both the user and outfit. Experimental results demonstrate the excellence of our proposed method over state-of-the-art methods in the fashion outfit recommendation.

In summary, the contribution of our proposed method can be summarized as below:

- We propose a novel knowledge-aware approach to sample negatives with hierarchical reinforcement learning strategy and introduce category-aware fashion rules.
- We utilize the rich information provided by KG to construct pseudo exposure data and design a novel rule-guided score function for negative sampling.
- The user-outfit pairs are transformed into the KG triples to explore the user- and outfit-aware negatives to improve the diversity of negative instances.

## 2 METHODOLOGY

#### 2.1 Overview of the Framework

The overall framework of RuleKG is shown in Fig. 2, which consists of a RL-based sampler and a recommender. For the sampler, we develop a hierarchical reinforcement learning strategy to perform the candidate negative instance selection. Given a positive user-outfit (u, o) pair with the "interact" relation  $r_0^+$ , the sampler generates the high-quality negatives  $e_f^u$  and  $e_f^o$ . For the recommender, the user's preference towards outfit matching rules concerning category compositions is encoded.

### 2.2 Rule Construction

To capture the user's distinctive preference over category combinations of the outfit, we aim to define a set of category-aware fashion rules, which are designed by referring to the outfit descriptions in Chinese provided by the internal dataset (*i.e.*, Alibaba-iFashion [3]) and the structured matching rules in English proposed in the external dataset (*i.e.* FashionVC [14]). There exists a cross-lingual language challenge to unify the rules of these two fashion outfit dataset. The rule defined in [14] is composed of a specific category pair with top and bottom. And we utilize EasyNMT<sup>1</sup>, a state-of-the-art neural

translation tool, to translate the fashion category name in English to that in mandarin. Category combinations with low co-occurrence frequencies are removed based on their occurrence in Alibaba-iFashion. If the description of a given outfit contains all the keywords in the rule, then it is supposed to trigger the specific rule. Since the outfits can be activated with more than one rule, the most fine-grained rule are determined based on the granularity score. For example, "T-shirt + tight skinny jeans" is selected over "top + bottom" as the final candidate rule for an outfit o. Because the former specifies the category combination in a more fine-grained manner thus achieves higher granularity score. The selected rule, denoted as  $v_0$  as shown in Eq. 6, is incorporated into the knowledge graph by establishing a connection between the target outfit node and the specific rule node with the newly appended relation "outfit\_has\_rule". And the user preference toward the outfit is further characterized by the interaction between user embedding  $\mathbf{e}_u$  and rule representation  $\mathbf{e}_{v_o}$ , capturing the user tastes in a fine-grained and interpretable manner.

## 2.3 Sampler

The task of the sampler is formularized as a hierarchical Markov Decision Process (MDP). More specifically, the overall task is decomposed into three levels of sub-tasks: 1) epoch-level 2) batch-level and 3) triple-level. Each task is defined as a 5-tuple MDP ( $S, A, T, R, \pi$ ), corresponding to a set of states, actions, state transition probabilities, reward and policy functions, respectively. The final candidate negatives selection aims to combine the uniformly sampled output from 2) and probability-distribution based output from 3) via the rule-guided score function.

**Pseudo Exposure Data.** The exposure data, indicating whether the exposed item has been interacted by the user, encodes important clues about the user's preference; however, such information is not always available. We propose to construct a pseudo exposure data which consists of three sets of user-outfit pairs: 1) clicked; 2) exposed but not clicked; and 3) non-observed entries, denoted as  $\xi_1, \xi_2, \xi_3$ , respectively. Here  $\xi = \{\xi_1, \xi_2, \xi_3\}$  denotes the whole entity set. Previous studies merely exploit the data from  $\xi_1$  and  $\xi_2$ , ignoring the side information provided by  $\xi_3$ .

**State.** The epoch-level task takes an action to construct the negative sampling neighbor set  $\xi_e$  for the triple-level based on the state feature  $s_e$ . It is defined as the difference between the consecutive epochs in terms of recall, precision, NDCG, hit ratio@K and the average reward obtained from the previous epoch of data. The state feature  $s_b$  of the batch-level task is calculated as the average reward from the previous epoch of data and that from the current batch, which aims to determine the candidate negative set  $\xi_b$  for uniform sampling. As for the triple-level task, which guides the agent to select the high-quality negatives over the neighbor set, the state feature  $s_t$  is represented as a tuple  $(e_t^u, r_0^-, e_t^o)$  with the initial state as  $(u, r_0^+, o)$ . Here  $r_0^+$  and  $r_0^-$  indicate the positive and negative interaction between the user u and outfit o, respectively.

Action and Policy. The action of the agent is regulated by the policy function set  $\pi = \{\pi_e, \pi_b, \pi_t^o, \pi_t^u\}$ . And  $\pi_e$  and  $\pi_b$ , determining which set within *S* to choose from, are implemented by a fully-connected (FC) layer and a softmax layer with the parameter  $W_e$ ,  $W_b$ , respectively. The negative instances of the triple-level task are generated by replacing either the user or the outfit node, termed

<sup>&</sup>lt;sup>1</sup>https://github.com/UKPLab/EasyNMT

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Fig. 2: The framework of the proposed RuleKG for outfit recommendation.

as user- and outfit-aware negatives. The policy  $\pi_t^u$  to select the user-aware negatives  $e_t^u$  is represented as the probability distribution among the neighbor set  $\mathcal{N}_u$  of target user node u, computed as below:

$$P(u', r_0^-, o|u, r_0^+, o) = \frac{\exp\left(f_G(u', r_0^-, o)\right)}{\sum_{u'' \in \mathcal{N}_u} \exp\left(f_G(u'', r_0^-, o)\right)},$$
(1)

where  $f_G$  represents the inner product between the embedding of  $\mathbf{e}_{u'}$ and  $\mathbf{e}_o$ , encoding their affinity in the entity space. Due to the space constraint, the description of  $\pi_t^o$  to select the outfit-aware negatives  $e_t^u$  is omitted, which performs in the similar manner.

**Final Negative Selection.** Given a positive triple  $(u, r_0^+, o)$ , the final negative instances  $e_f = \{e_f^o, e_f^u\}$  are chosen based on the ruleguided user preference score of the samples generated from the triple-level and the batch-level task, denoted as  $(e_t^o, e_t^u)$  and  $(e_b^o, e_b^u)$ , respectively. Here we take the outfit-aware negative instances  $e_f^o$  for demonstration and that for the user-aware negative sampling of  $e_f^u$  follows the similar manner. The final selection of  $e_f^o$  is formalized as below:

$$e_{f}^{o} = \begin{cases} e_{t}^{o}, & y(u, e_{t}^{o}, v_{t}^{o}) >= y(u, e_{b}^{o}, v_{b}^{o}) \\ e_{b}^{o}, & y(u, e_{t}^{o}, v_{t}^{o}) < y(u, e_{b}^{o}, v_{b}^{o}), \end{cases}$$
(2)

where  $v_b^o$  and  $v_t^o$  indicate the mapped rule for  $e_b^o$  and  $e_t^o$ , respectively. The user preference modeling function incorporating the rules is represented as follows. Here  $\mathbf{e}_{v_t^o}$  refers to the rule embedding of outfit  $e_t^o$ .

$$y(u, e_t^o, v_t^o) = \langle \mathbf{e}_u, \mathbf{e}_t^o \rangle + w_3 * \langle \mathbf{e}_u, \mathbf{e}_{v_t^o}^o \rangle, \tag{3}$$

where  $w_3$  is the coefficient balancing the score between the user preference over the outfit and that over the rule.

**Reward.** Inspired by [22], the reward function  $\mathcal{R}(e_t)$ , reflecting the quality of the sampled negatives, as shown below:

$$\mathcal{R}(e_f) = w_1 * (\langle \mathbf{e}_u, \mathbf{e}_f \rangle + \langle \mathbf{e}_o, \mathbf{e}_f \rangle) + w_2 * \sigma(\beta \langle \mathbf{e}_u, \mathbf{e}_f \rangle), \quad (4)$$

where  $\beta$  and  $\sigma$  refer to the scaling factor and the sigmoid function, respectively. Here  $w_1$  and  $w_2$  denote the weighting coefficient.

**Objective Function.** Since the sampling process involves discrete sampling and SGD [13] cannot be directly utilized to compute the gradients. The REINFORCE [16] is introduced to solve this issue,

and we maximize the following cumulative discounted reward. The gradients of  $L_S$  with respective to the sampler parameter  $\theta_S$  is calculated as follows:

$$\nabla_{\theta_S} L_S = \nabla_{\theta_S} \sum_{e_f^u \in C_u} \mathbb{E}_{\pi_t^u} [\mathcal{R}(e_f^u)] + \nabla_{\theta_S} \sum_{e_f^o \in \xi_e} \mathbb{E}_{\pi_t^o} [\mathcal{R}(e_f^o)]$$
(5)

where *N* refers to the number of triples  $(u, r_0, o)$  in the training set  $\Omega$ .

#### 2.4 Recommender

To learn the recommender model with the implicit feedback, the Bayesian Personalized Ranking (BPR) [12] is utilized to ensure that the user preference score of the positive feedback  $(u, r_0^+, o)$  is larger than of the negative triple  $(u, r_0^-, e_f^o)$  or  $(e_f^u, r_0^-, o)$ . The model is trained by jointly optimizing the user- and the outfit-aware BPR ranking loss, represented as  $\ell_u$  and  $\ell_o$ , respectively.

$$\ell_{u} = \sum_{\Omega} \log \left( 1 + \exp(-(y_{(u,o,v_{o})} - y_{(e_{f}^{u},o,v_{o})}))) \right), \tag{6}$$

and the proposed outfit-aware ranking loss  $\ell_u$  is denoted as below:

$$\ell_o = \sum_{\Omega} \log \left( 1 + \exp(-(y_{(u,o,v_o)} - y_{(u,e_f^o,v_f^o)})) \right).$$
(7)

Here  $v_o$  and  $v_f^o$  represent the activated rule node for outfit o and  $e_f^o$ , respectively. And the final overall objective loss for the recommender is shown in the following:

$$L_R = \lambda_1 \ell_u + \lambda_2 \ell_o + \gamma ||\theta_R||_2^2, \tag{8}$$

where  $\lambda_u$  and  $\lambda_o$  denote trade-off parameters. The last term is the L2 regularizer loss, which imposes the constraint on the recommender parameters  $\theta_R$  to prevent overfitting.

#### **3 EXPERIMENTS**

#### 3.1 Experimental Settings

3.1.1 Dataset Description. Two publicly available datasets from different domains are utilized for evaluating the performance of RuleKG: Alibaba-iFashion dataset [3] and Last-FM released by [21]. Since our focus is on the top+bottom outfit recommendation, we

 
 Table 1: Performance evaluation with state-of-the-art baselines on two benchmark datasets.

Method	Alibaba-iFashion			Last-FM		
	recall@20	ndcg@20	re	call@20	ndcg@20	
BPRMF	0.0809	0.0468	(	0.0687	0.0584	
CKE	0.0819	0.0471	(	0.0732	0.0630	
KGAT	0.1033	0.0589	(	0.0873	0.0744	
KGPolicy	0.1189	0.0717	(	0.0957	0.0837	
RuleKG	0.1284	0.0766		0.1010	0.0926	

 

 Table 2: Performance with variants of the framework by removing rule and candidate selection modules.

Model Variant	Alibaba-iFashion			
	recall@20	ndcg@20		
RuleKG	0.1284	0.0771		
w/o RULE	0.1263	0.0756		
w/o FCS	0.0941	0.0551		
w/o UA	0.0946	0.0552		
w/o OA	0.0779	0.0443		

conduct data preprocessing to filter out irrelevant items (*e.g.*, shoes, accessories) based on the relations (*i.e.*, item categories) provided by knowledge graph triples and outfits' textual descriptions. The final dataset consists of 24 962 outfits with only tops and bottoms retained. Among 114,728 users, about 90% of them have less than 20 interactions.

3.1.2 Implementation Details. The proposed RuleKG is implemented in Pytorch. The embedding size d is set as 64 in the collaborative knowledge graph (*i.e.*, relations, user, item and entity nodes) during representation learning. For the neighbor sampling, the size of the adjacency map for each node is set as 128 to involve sufficient neighbors for candidate selection. Adam optimizer [8] is leveraged for model update and the batch-size is fixed to 1024.

**3.1.3** Baselines. We compare the proposed RuleKG with the following traditional negative sampling methods and knowledge-graph based approaches.

- **BPRMF** [12]: the negatives are randomly sampled with uniform probability with the classical matrix factorization (MF) model as the recommender.
- CKE [29] integrates the latent representation learnt from collaborative filtering algorithm and structural representations from TransR.
- **KGAT** [20] proposes an attention-based GCN and models the high-order connectivity among entities.
- **KGPolicy** [22] proposes to discover the high-quality negatives over the knowledge graph using the structure neighborhood information.

## 3.2 Performance Comparison and Ablation Study

Table 1 shows the comparison results and we can find that the proposed RuleKG outperformed the best performing state-of-the-art KGPolicy [22] by a large margin. It demonstrates the effectiveness of the proposed rule-guided recommender and the negative sampler in obtaining the high-quality negative instances. And the knowledge embedding method (i.e., CKE) achieves much inferior results than GNN-based emthod, which proves that the capability of graph-based neural networks in information propagation.

To demonstrate the significance of the key component in the proposed framework, we compare the variants of RuleKG by removing the core module: constructed fashion rules (w/o RULE), final candidate selection (w/o FCS), outfit-aware negatives (w/o OA) and user-aware negatives (w/o UA). The results are shown in Table 2. From the results, we can observe that the user-aware negatives

improve the performance substantially. The final candidate selection module with sampling on two different sets also enhances the performance.

## 3.3 Case Study

We utilize the domain knowledge embedded in the knowledge graph and category-aware rich semantics provided by the constructed rules. Fig. 3 qualitatively demonstrates the importance of such auxiliary information. We randomly choose a user, the exemplar outfits compositions shown indicate that the target user has a preference over outfits with sweater + skirts. From the top-3 ranked results recommended by our model, we can find that it accurately captures the user's taste for such category combinations.

User 5611942b51a56cdd25d2a29fb7aaf270



Fig. 3: Visualization of top-3 recommendation results (w/ and w/o rule). Best viewed in color.

## 4 CONCLUSION AND FUTURE WORK

In this paper, we present a novel rule-guided recommender with the knowledge-aware sampler to perform personalized outfit recommendation. A novel user preference score function is designed, capturing the user's taste toward category combinations in both the implicit and explicit manner. Experiments demonstrate the effectiveness of the proposed framework in modeling the user's preference and fully utilizing the rich facts provided by knowledge graph. In the future, we aim to incorporate user reviews of the outfits to develop explainable knowledge-aware recommendation models and generalize it to more real-world scenarios. Rule-Guided Knowledge-Graph based Negative Sampling for Outfit Recommendation

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